

## Topics on topological robotics

# On topological complexity of Eilenberg-MacLane spaces and effective topological complexity

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IN POZNAŃ

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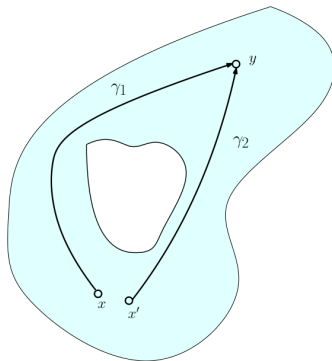
A motion planning algorithm is a map  $s: X \times X \rightarrow PX$  s.t.  $\pi \circ s = \text{id}_{X \times X}$ , i.e. a section of  $\pi$ .

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A motion planning algorithm is a map  $s: X \times X \rightarrow PX$  s.t.  $\pi \circ s = \text{id}_{X \times X}$ , i.e. a section of  $\pi$ . It exists iff  $X \simeq *$ .



A topological feature of the configuration space inducing instability on the motion planning.

# Topological complexity and sectional category

**Topological complexity** (Farber '01)  $TC(X) = \min k$  s.t.  $\exists \{U_i\}_{0 \leq i \leq k}$  open cover of  $X$  with (cont.) local sections of  $\pi: PX \rightarrow X \times X$ .

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$$(\text{Rudyak, '10}): p_r: PX \rightarrow X^r \quad p_r(\gamma) = \left( \gamma(0), \gamma\left(\frac{1}{r-1}\right), \dots, \gamma\left(\frac{r-2}{r-1}\right), \gamma(1) \right).$$

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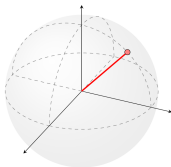
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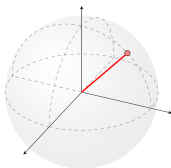
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As  $\text{secat}$  is homotopy invariant,  $TC_r(X) = \text{secat}(\Delta_r: X \hookrightarrow X^r)$ .

# Some robots and their complexities!

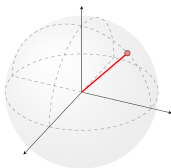


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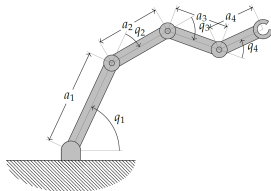


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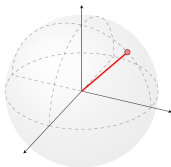
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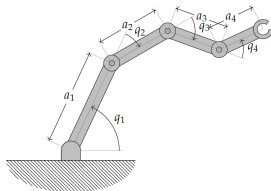
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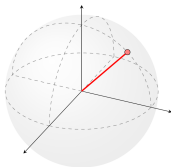


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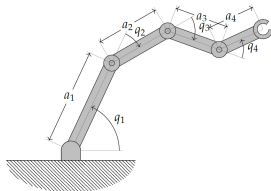


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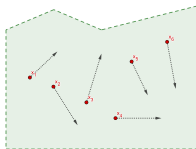
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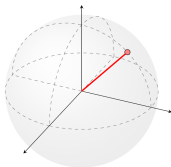
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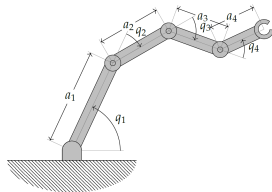
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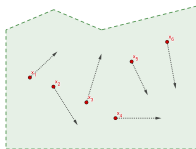
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$$TC(F(\mathbb{R}^m, n)) = \begin{cases} 2n - 2 & \text{for all } m \text{ odd} \\ 2n - 3 & \text{for all } m \text{ even} \end{cases}$$

(Farber-Yuzvinsky '04, Farber-Grant '08)

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**An interesting homotopy invariant** connected with classic invariants ( $\text{LS-cat}$ ,  $\text{secat}$ ...) with its own open problems like the **Eilenberg-Ganea problem**.

# The Eilenberg-Ganea problem

$$K(G, 1) \quad \begin{cases} \pi_1(K(G, 1)) = G \\ \pi_k(K(G, 1)) = 0 \end{cases}.$$

$G$  is **geometrically finite** if  $\exists$  a finite CW model for  $K(G, 1)$ .

Define the **(sequential) topological complexities of a group** by

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The problem remains open.

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- Dranishnikov '17, Cohen-Vandembroucq '17:  $N$  closed non-orientable surface,  $N \neq \mathbb{R}P^2 \Rightarrow TC(N) = 4$ .
- Farber-Mescher '20: lower bound by dimensions of centralizers.
- Dranishnikov '20:  $G$  hyperbolic,  $G \not\cong \mathbb{Z} \Rightarrow TC(G) = 2cd(G)$ .
- Farber-Grant-Lupton-Oprea '19: bounds via Bredon cohomology and  $TC^{\mathcal{D}}$ .

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- Basabe-González-Rudyak-Tamaki '14:  $TC_r(\mathbb{Z}^n) = (r-1)cd(\mathbb{Z}^n) = (r-1)n$ .
- Farber-Oprea '19: generalize FGLO bounds.
- Hughes-Li '22:  $G$  hyperbolic,  $G \not\cong \mathbb{Z} \Rightarrow TC_r(G) = rcd(G)$ .

## Sectional category of subgroup inclusions

For  $\iota: H \hookrightarrow G$  define the **sectional category of the monomorphism  $\iota$**  by

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## Theorem (EB, Farber, Mescher, Oprea)

Let  $N \triangleleft G$  and  $\pi: G \rightarrow Q = G/N$  the projection. Then

$$\text{cd}(\pi: G \rightarrow Q) \leq \text{secat}(N \hookrightarrow G) \leq \text{cd}(Q).$$

If  $\pi^*: H^{\text{cd}(Q)}(Q, A) \rightarrow H^{\text{cd}(Q)}(G, \pi^* A)$  is non-zero then  $\text{secat}(N \hookrightarrow G) = \text{cd}(Q)$ .

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To go further, we use some **homological algebra**! But first just a bit of **equiv. homotopy**...

# $\mathrm{secat}(H \hookrightarrow G)$ and classifying spaces of families

Denote  $E_{\langle H \rangle} G$  as the **classifying space for the family of subgroups** generated by  $H$ .

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## Theorem (Błaszczyk, Carrasquel, EB)

secat( $H \hookrightarrow G$ ) coincides with min.  $n \geq 0$  s.t.  $\rho: EG \rightarrow (E_{\langle H \rangle} G)_n$  can be factorized up to  $G$ -homotopy as

$$\begin{array}{ccc} EG & \xrightarrow{\rho} & E_{\langle H \rangle} G \\ & \searrow \text{dashed red} & \nearrow \text{blue} \\ & (E_{\langle H \rangle} G)_n & \end{array}$$

We also introduce **Adamson cohomology** in the investigation.

## secat and $TC_r$ as $\mathcal{A}$ -genus

$G$  group,  $X$  a  $G$ -space,  $\mathcal{A}$  family of  $G$ -spaces.

$$\mathcal{A}\text{-genus}(X) := \min\{k \in \mathbb{Z}^+ \mid \exists \{U_i\}_{0 \leq i \leq k}, U_i \subset X \text{ open s.t.} \\ \forall 0 \leq i \leq k \exists A_i \in \mathcal{A} \text{ and } G\text{-equiv } U_i \rightarrow A_i\}$$

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## Theorem (EB)

Let  $X$  be a path conn. CW-complex with  $\pi_1(X) = \pi$ . If  $q: \widehat{X} \rightarrow X$  is a conn. covering:

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### Corollary (EB)

Let  $\pi$  be a torsion-free group, and  $K \leq \pi^r$  subconj. to  $\Delta_{r,\pi}$ .

- (a)  $TC_r(\pi) \leq \mathcal{A}\text{-genus}(E_{\mathcal{F}}(\pi^r))$  for  $\mathcal{F}$  any full family of  $\pi$ .
- (b)  $TC_r(\pi) \leq \text{cd}_{\langle K \rangle} \pi^r$ .
- (c)  $TC_r(\pi) \leq \text{cd}(\pi^r / K)$  if  $K \trianglelefteq \pi^r$ .

# The Bernstein-Schwarz relative class

For  $H \leq G$  we define the **relative augmentation ideal**

$$\sigma: \mathbb{Z}[G/H] \rightarrow \mathbb{Z} \quad \sigma \left( \sum_{x \in G/H} n_x \cdot x \right) = \sum_{x \in G/H} n_x \quad I := \ker \sigma$$

The **Bernstein-Schwarz class of  $G$  relative to  $H$**  is  $\omega \in H^1(G, I)$  represented by

$$\xi \in \operatorname{Hom}_{\mathbb{Z}[G]}(\mathbb{Z}[G] \otimes K, I), \quad \xi = \mu \circ (\varepsilon \otimes \operatorname{id}_K) \quad K \text{ augm. ideal} \quad \mu: K \rightarrow I$$

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## Theorem (Błaszczuk, Carrasquel, EB)

- $\omega \in \ker[H^1(G, I) \xrightarrow{i^*} H^1(H, I)]$ .
- If  $\omega^k \neq 0 \implies \text{secat}(H \hookrightarrow G) \geq k$ .
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- $\text{secat}(H \hookrightarrow G) = \text{cd}(G) \iff \omega^{\text{cd}(G)} \neq 0$ .

A class  $\alpha \in H^n(G, A)$ ,  $\alpha \neq 0$  is **essential relative to  $H$**  if  $\exists \varphi: I^n \rightarrow A$  s.t.  $\varphi_*(\omega^n) = \alpha$ .

## Lower bounds for $\text{secat}$ and $\text{TC}_r$

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$$\text{secat}(H \hookrightarrow G) \geq \text{cd}(G) - \kappa_{G,H} \quad \kappa_{G,H} := \max\{\text{cd}(H \cap xHx^{-1}) \mid x \in G \setminus H\}.$$

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(Grant '22) The **parametrized TC of epim.  $\rho$**   $\text{TC}[\rho: G \twoheadrightarrow Q] = \text{secat}(\Delta: G \hookrightarrow G \times_Q G)$

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# From $K(G, 1)$ to symmetries

Now we look at TC not of  $K(G, 1)$  but of **G-spaces (symmetries)**!

# Motion planning and symmetries

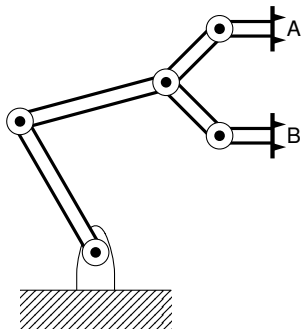
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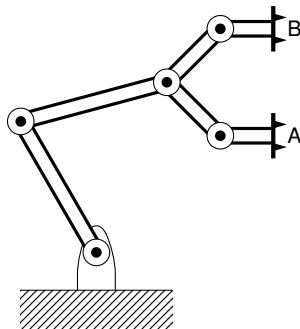
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State 1



State 2

Two different but functionally equivalent states of the robot arm.

# Effective TC and cat

Define  $\mathcal{P}_k(X) = \{(\gamma_1, \dots, \gamma_k) \in (PX)^k \mid G\gamma_i(1) = G\gamma_{i+1}(0) \text{ for } 1 \leq i \leq k\}$ .

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If  $G \rightarrow P \rightarrow B$  **principal  $G$ -bundle**,  $TC^{G,\infty}(P) \leq TC(B) \leq 2(\dim(P) - \dim(G))$ .

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Furthermore, if  $|G| \leq cd(X)$ , then

$$TC^{G,2}(X) > 0.$$

# ¡Gracias por su atención! Thank you for your attention! Dziękuję za uwagę!

Papers part of this dissertation:

- “On the sectional category of subgroup inclusions and Adamson cohomology theory”. Joint with [Z. Błaszczyk](#) and [J. G. Carrasquel-Vera](#). Published in [J. Pure and Appl. Alg.](#) vol. 226, issue 6, June 2022, 106959.
- *Sectional category and sequential topological complexity of aspherical spaces as  $\mathcal{A}$ -genus*. Preprint.
- *On properties of effective topological complexity and effective Lusternik-Schnirelmann category*. Joint with [Z. Błaszczyk](#) and [A. Viruel](#). To appear in [Proc. R. Soc. Edinb., Sect. A, Math.](#)
- *Sequential topological complexity of aspherical spaces and sectional category of subgroup inclusions*. Joint with [M. Farber](#), [S. Mescher](#) and [J. Oprea](#). Published in [Math. Ann.](#) (online).

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